

SIS72 – Automated Driving Technology Research in Japan

Dynamic Map

September 11, 2014 Masao FUKUSHIMA NISSAN MOTOR CO.,LTD



Dynamic Map for Autonomous Drive

Proposal of DM (Dynamic Map) for Autonomous Drive

- Create detailed drive route based on precise map information and traffic regulation information
- Recognize accurate vehicle position by comparing GPS with DM
- Grasp vehicle surrounding condition by combination of map and traffic / road information

by Public & Private sectors collaboration.



DM Hierarchical Structure

■ Many kinds of information should be included in DM (Dynamic ←→ Static)

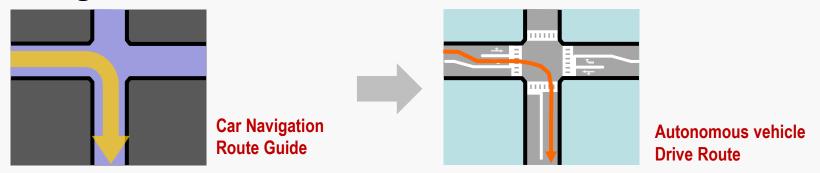
DM Hierarchical Structure

Dynamic < 1 sec	Vehicle current position Surrounding vehicles / pedestrians Traffic signal info.	_
Semi Dynamic < 1 min	Traffic accident info. Traffic congestion info. Local weather info.	14
Semi Static < 1 hour	Traffic regulation info. Road works info. Wide area weather info.	N.
Static < 1 month	Traffic signal / Landmark position (3D) Road location / traffic sign position (3D) Road section ID / Intersection ID Road shape (Local roads) Road shape (Main roads)	100

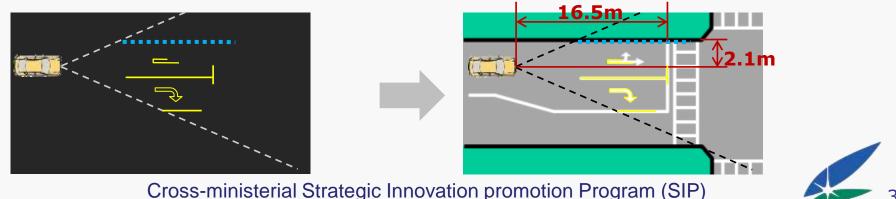


DM Usage Example 1

Create detailed drive route based on precise map information and traffic regulation information.



Recognize accurate vehicle position by comparing GPS with DM.



DM Usage Example 2

Grasp vehicle surrounding condition by combination of map and traffic / road information.

System cannot know a vehicle ahead is parking or in the end of queue System understand a vehicle ahead is in the end of queue. Never overtake this car. Traffic Jam! End of queue is here!

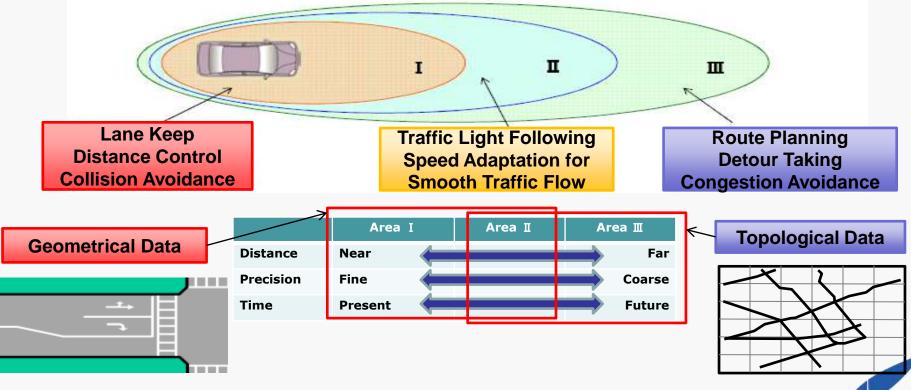
Enhancement of Outside Condition Sensing

Get more reliable outside information by double source, map and on-board sensors. By DM By on-board By DM By on-board

		including v2x	sensors
Dynamic < 1 sec	Vehicle current position Surrounding vehicles / pedestrians Traffic signal info.		>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>
Semi Dynamic < 1 min	Traffic accident info. Traffic congestion info. Local weather info.	>>> >>	(✔) (✔)
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Static < 1 month	Traffic signal / Landmark position (3D) Road location / traffic sign position (3D) Road section ID / Intersection ID Road shape (Local roads) Road shape (Main roads)	(\checkmark) (\checkmark) (\checkmark) (\checkmark) (\checkmark) (\checkmark)	

Proper Information

Outside data sources are used properly depending on the distance from the autonomous vehicle.



DM Prototype

DM prototype will be prepared and tested by end of this fiscal year. (March 2015) The test result is reflected to the first version



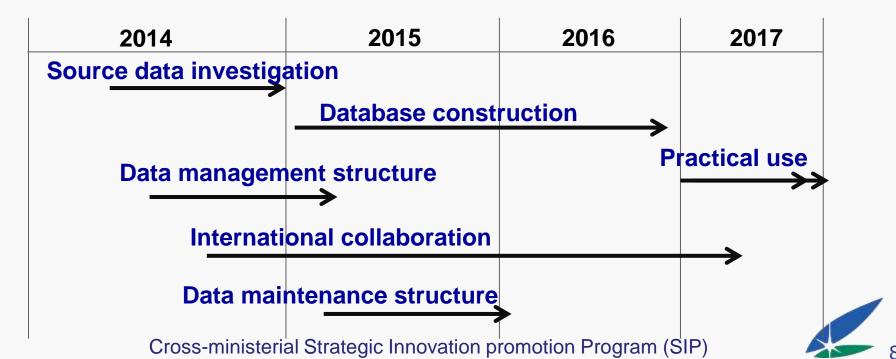
of DM specification.

Test area includes, busy traffic on ordinary road, busy intersections, shopping streets, express ways, several highway interchanges, tall (ETC) gates.

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Schedule

Public & Private sectors collaboration has already started. 2014: Preliminary investigation phase 2015-16: Development phase 2017: Practical use



Summary

- In order to realize highly smarter autonomous drive, map data-base having not only static information but also dynamic information is necessary.
- Public & Private sectors collaboration has already started. DM (Dynamic Map) hierarchical structure has been under discussion.
- Expected schedule is as follows,
 - 2014: Preliminary investigation phase 2015-16: Development phase 2017: Practical use



Thank you for your attention.

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